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How to write a review Tell us what you think about this product, you can download it for free and you can leave your review as share your experience about it. At today's press conference for the Carnegie Mellon University Robotics Institute's (CMU-RI) new Humanoid Robot, Humanoids spelled out their plans for making robots that are not only able to walk, but able to adapt to new situations. The CMU-RI Humanoids presented their work in the form of a video, which features a team member walking past the press conference stage while also demonstrating his robot's movement capabilities. While this isn't at the level of an actual talking robot (yet), it is a major step in the right direction. The video from yesterday (below) shows that the CMU-RI Humanoids are already designed with leg movements that seem like natural movements for a person. Each leg is made up of two different sections, a thigh and a shank. The research is clearly focused on building legs for walking bipedalism with high stability. Stability is a big issue for humans walking, which seems to have been solved. The video also shows the two CMU-RI Humanoids during walking tests. One is on the ground, and the other is in mid-air. And yes, the two robots walk side-by-side. The video shows that the robots are able to keep their balance while walking up and down stairs, as well as moving from a stable resting position to a point in mid-air. [Video Description CMU Robot Stabilizes on Balancing Sticks](#) In a paper published at the American Physical Society's March Meeting, Humanoids will present a case study showing the robot balancing on a pair of balancing sticks. They are planning on using this technique for how a robot can walk on uneven surfaces. This video (below) is a short clip of the CMU-RI Humanoids walking on a pair of balancing sticks. The video was created from a series of eight different takes of the robot in motion while walking on sticks. [Video Description CMU-RI Robot Balances on Two Balancing Sticks](#) Each robot has four infrared sensors, a force plate, and a pair of balancing sticks. This research will be published at the American Physical Society's March Meeting. While it is not at the level of a talking robot, the research represents a major leap in

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